

SERIES EMAX-RO

Rotative Magnetic Absolute Encoder



- Magnetic Single-turn Absolute Encoder
- Angular measurement without bearing
- High resolution, 16000 measuring steps / turn
- Additional incremental signals for highly dynamic drives
- Diverse Interfaces available:
 - Standard: SSI or CANopen
 - On request: RS422, RS422 (addressable), RS232, CAN BASIC ELGO
 - In preparation: BISS-C

EMAX-RO - Rotative Magnetic Absolute Encoder

General: The angle measuring system EMAX-RO is a combination of a sensor and a magnetic ring. The magnetic ring is mounted directly to an engine shaft or an axle. This ensures a quick and easy installation. EMAX-RO is especially suited for measuring rotative angles. The sensor head with its high protection class is resistant against any kind of dust and dirt and works completely without wear.

Furthermore, the rotative measuring system EMAX-RO has the advantage of absolute measurement and therefore belongs in the category of single turn encoders.

Essential features:

- Rotative angle measuring system
- Resolution of 16000 measuring steps over 360° (other resolutions on request)
- Absolute measurement
- Different interfaces are available
 Absolute: Standard: SSI or CANopen
 On request: RS422, RS422 (addressable),
 RS232 or CAN BASIC ELGO
 In preparation: BISS-C
 Incremental: 90° phase shifted square-wave signals
 (TTL or HTL) or 1 Vss sine/cosine signals
- Direct measurement on engine shaft or axis possible
- No wear thanks to contact-free measuring principle



The magnetic ring: The magnetic ring that is included in the delivery has a diameter of 50.95 mm (max. 1000 rpm) or 51.50 (max. 20000 rpm) in the version with protection ring.

Caution: the measuring system may only be operated with the corresponding magnetic ring!

Distance between ring and sensor: The ideal distance between the magnetic ring and the active sensor area of the measuring system is between 0.5 ... 1.0 mm <u>without</u> protection ring and max. 0.45 mm <u>with</u> protection ring. Outside this area, proper functioning of the device cannot be guaranteed!

Dimensions sensor:





Technical Data:

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Measuring principle	Absolute		
Repeat accuracy	+/- 1 Increment		
System accuracy in $\mu \mathrm{m}$ at 20 °C	+/- $(150 + 20 \times L)/$ +/- 0,35° (type designation 010) +/- $(50 + 20 \times L)/$ +/- 0,16° (type designation F10)		
Sensor distance to magnetic Ring	max. 1.0 mm (without protection ring) max. 0.45 mm (with protection ring)		
Basic pole pitch	5 mm		
Sensor housing material	Zinc die cast		
Housing dimensions	L x W x H = 62 x 40 x 20 mm		
Required magnetic ring	MR 00 051 030 206 0032 050 2 14021 (without protection ring) MR 00 052 030 206 0032 050 2 14021 (with protection ring)		
Max. measuring range	360°		
Connection type	Circular plug M12 on housing		
Weight	130 g (without cable) Cable (accessory): approx. 60 g per meter		
Ambient conditions			
Operating temperature	-10 +70 °C (-25 +85 °C) on request		
Storage temperature	-25 +85 °C		
Protection type	IP40 (standard), IP65 (option V)		
Electrical data			
Supply voltage	10 30 VDC		
Ripple	<5 %		
Current consumption	max. 150 mA		
Interfaces	Standard: SSI (Gray or binary), CANopen On request: CAN BASIC ELGO, RS232, RS422 or addressable RS422 In preparation: BISS-C		
Resolution	16000 measuring steps/revolution		
Max. rotation speed	 20000 rev./min. (depending on interface) 0 to 1000 rpm without protection ring 1000 to 20000 rpm with protection ring 		
Sensor cable	max. 30 m (depending on interface)		

Examples:

EMAX-RO with SSI binary interface, 25 bit and circular plug

EMAX-RO after ELGO standard with CANopen (DS406) interface, 12 pin round connector, Bitrate125 kbit/s and device address: 0

Order Designation:

For orders, please use the following order key:

RM				
٨		har		
A		liber		
	00	0 99		
В	Signal co	able length (cable length in dm)		
	000	0 m - (standard version without cable)		
\sim	Resolutio	on in Um		
C	010	0 = 10 µm with system accuracy in μ m + (150 + 20 m)		
	F10	$10 \mu\text{m}$ - with system accuracy in μm +/- ($100 \pm 20 \text{x}$ L)		
	110			
D) Interface			
	SBO	SSI-Interface (25 Bit binary code)		
	SG0	SSI-Interface (25 Bit Gray code)		
	CA0	CANopen (DS406)		
	CN0	CAN BASIC ELGO (on request)		
	420 420	addressable RS/22 (on request)		
	230	RS232 (on request)		
Е	Bit rate			
	09k6	9600 Bit/s - standard bit rate for RS422 (420/A20)		
	19k2	19200 Bit/s tor RS422		
	38k4	38400 Bit/s for R5422		
	120K	250000 Bit/s for CAN		
	500k	500000 Bit/s for CAN		
	1MHz	1000000 Bit/s for CAN		
	Addition	al options		
	F	Device address 0 E		
=	•	(standard settina: device address 0)		
		standard version		
G				
	V	Standard version always with 12-pin M12 round connector		
ı	A	williou leffiling resision		
•	Inkrementalsianale			
L	H2N5	incremental square wave signals HTL with 2.5 μ m resolution		
	H005	incremental square wave signals HTL with 5 μ m resolution		
	H010	incremental square wave signals HTL with 10 μ m resolution		
	H025	incremental square wave signals HTL with 25 μ m resolution		
	12N5	incremental square wave signals 11L with 2.5 μ m resolution		
	1005	incremental square wave signals 11L with 5 μ m resolution		
	T025	incremental square wave signals TTL with $25 \mu m$ resolution		
	SC50	sine-cosine signal 1 Vss. 5 mm pole pitch		

Note: options that are not required are filled in with "-"!

1

Dimensions of the magnetic ring:



Without protection ring Usage up to max. 1000 rpm

Screw mounting example:

With protection ring Usage up to max. 20000 rpm

Magnetic ring - Installation suggestions:



Adhesive mounting example:



Accessories:

Magnetic ring	MR 00 051 030 206 0032 050 2 14021 (without protection ring) MR 00 051 030 206 0032 050 2 14021 (with protection ring) Resolution 16 000 steps per turn
PNO1	SSI / PROFIBUS Converter
DKA-00-RCF0-050-XXXX-12-T-D-S	Connection cable for EMAX-RO, device side with 12-pol. M12- plug female, cable length 5.0 m, evaluation unit with open wires, 12 wires, twisted pair, drag chain suitable, with shield

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